



Pack 03 BUILD INSTRUCTIONS

ASSEMBLING THE FINGERS ASSEMBLING THE THUMB ASSEMBLING THE LEFT HAND ASSEMBLING THE LOWER LEFT ARM



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Advice from the experts

Please keep ALL unused screws as they may be required in a later stage.

Please make sure you don't mix up the screws. They look quite similar, but the threads do vary slightly. Using the wrong screws may damage the parts.

When securing parts together using multiple screws, fit each screw loosely to ensure all the parts are correctly aligned before gently tightening them firmly, but not overtight, in the order in which you placed them.

The screwdriver can be magnetized by stroking it with a magnet (fridge magnet, etc.) enabling it to hold the screws and make assembly easier.

If a screw is tight going into a metal part, do not force it as you may shear the head off. Remove it and put a tiny smear of Vaseline, soap or light oil on the thread. That will lubricate it and make it easier to drive home.

Some parts will require a little glue for assembly. Please apply glue sparingly and use a cocktail stick so that you don't use too much nor apply the glue too heavily. We recommend superglue gel or Extra Thin Liquid modeling glue. Where possible, parts should be test-fitted in place before gluing.

Look out for the glue symbol and apply glue to the red area indicated in the picture.

During the course of this build, you will receive many pieces that you will assemble immediately – following the instructions in the corresponding stage – and other pieces that you should store in the tray supplied, for use in future assembly stages.

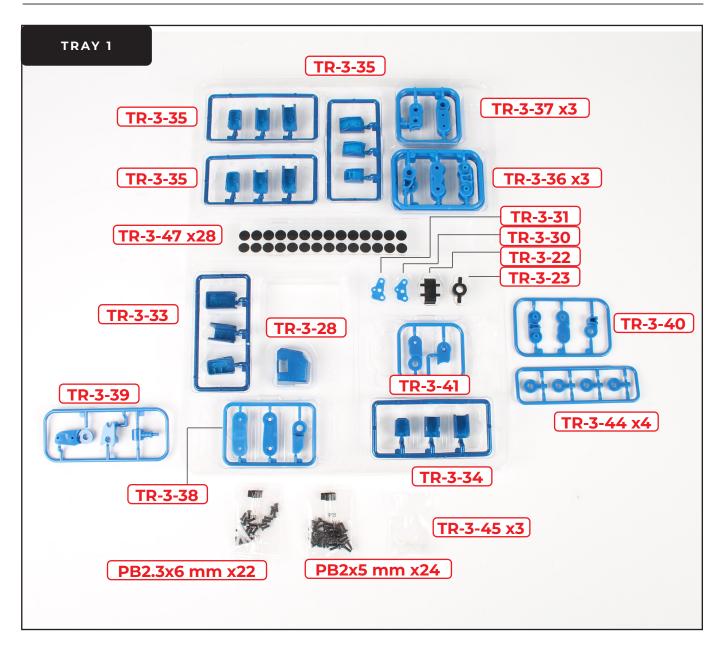
Always protect the paint finish on components by placing a cutting mat, sheet of white paper or soft cloth on your work surface.

Left and Right! When building your Optimus Prime, the left or right hand side refers to each side as viewed by Optimus Prime. Optimus Prime's left arm is on the viewer's right.

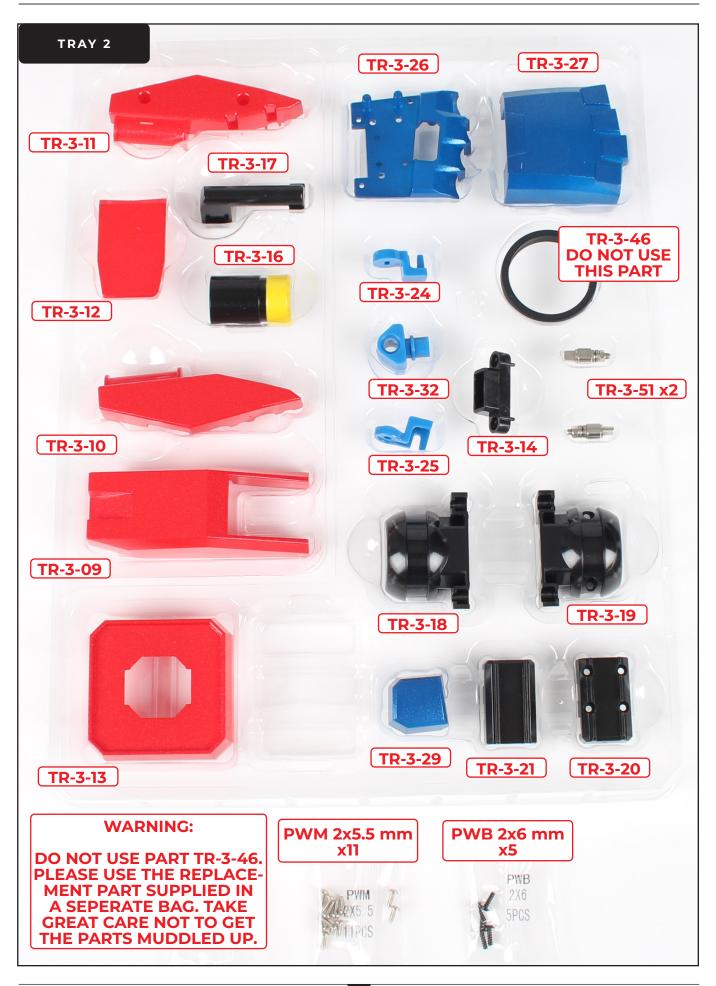
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WARNING: Some parts are assembled using magnets. These magnets can cause serious injury if they are swallowed. Keep away from children. If you suspect a magnet has been swallowed, seek medical help straight away.

Pack 3 Parts



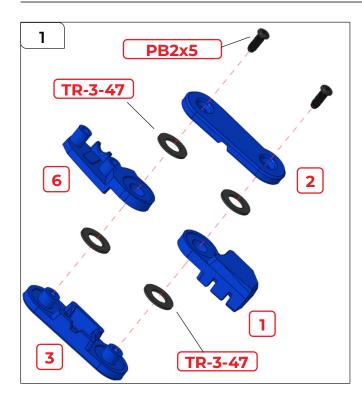
Pack 3 Parts



Pack 3 Parts



Assembling the Thumb

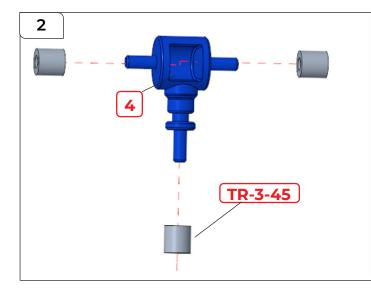


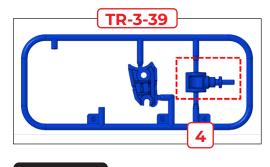
STEP 1

NOTE: when removing parts from the sprues, we recommend snapping them off rather than using sprue cutters in order to preserve the paintwork.

Snap No.s 1, 2, & 3 from sprue **TR-3-38.** Snap No. 6 from sprue **TR-3-39.** Place **2x TR-3-47** onto 3. Place **2x TR-3-47** onto 1 and 6. Place 1 and 6 onto 3. Wriggle them back and forth to get a tight fit otherwise the casings won't fit at a later stage. Place 2 onto 1 and 6, then secure the assembly

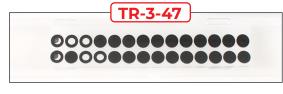
Place 2 onto 1 and 6, then secure the assembly together using **2x PB2x5 mm** screws.







Snap No. 4 from sprue **TR-3-39** Place **3x TR-3-45** onto 4.

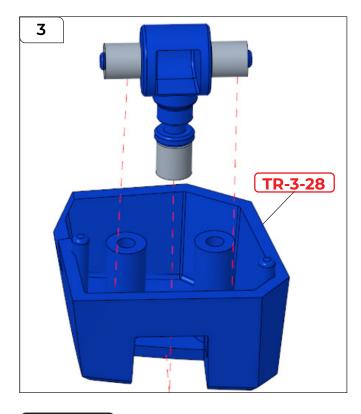


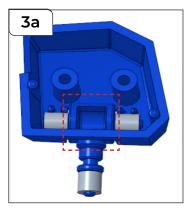
TR-3-38

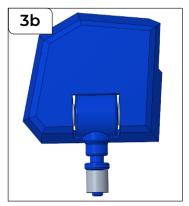
2

TR-3-39

Assembling the Thumb

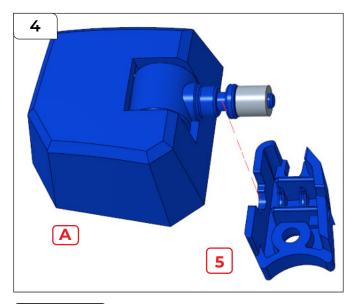


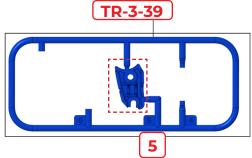




STEP 3

Place the assembly from step 2 onto **TR-3-28**, paying close attention to the orientation, as shown in 3a and 3b.

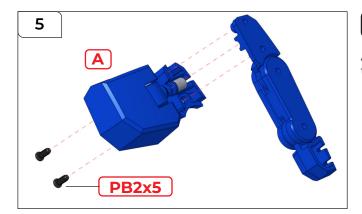






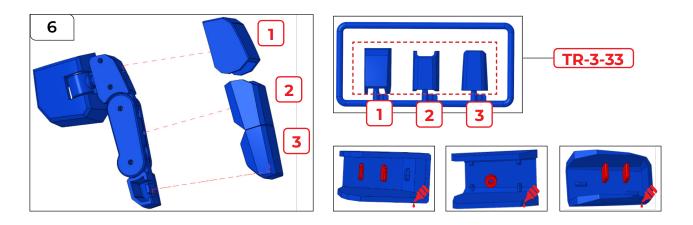
Snap No. 5 from sprue **TR-3-39**. Place 5 onto A.

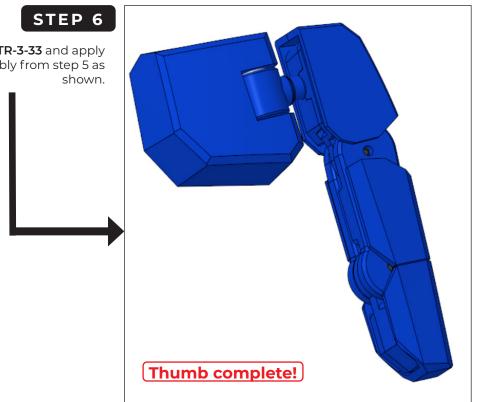
Assembling the Thumb



STEP 5

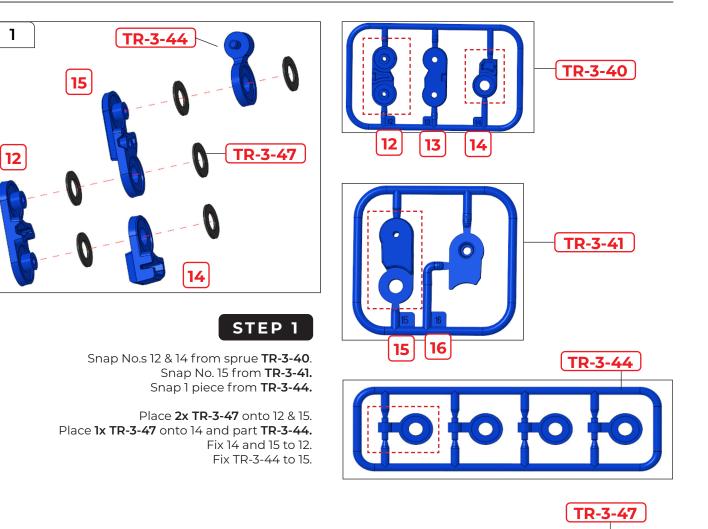
Attach A to the assembly from step 1 and secure the parts together using **2x PB2x5 mm** screws.





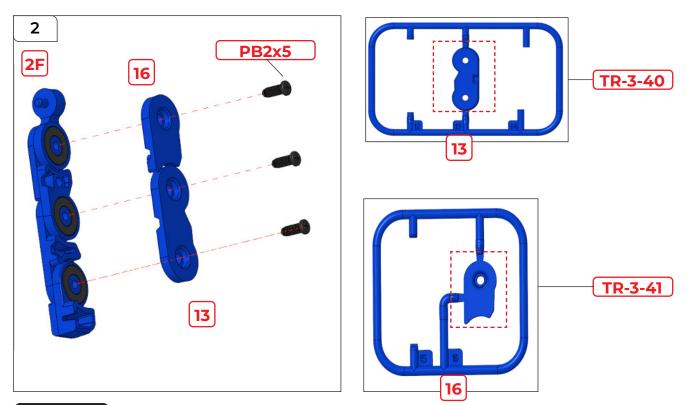
Snap No.s 1, 2 & 3 from sprue **TR-3-33** and apply glue as shown. Fix to the assembly from step 5 as shown.

1



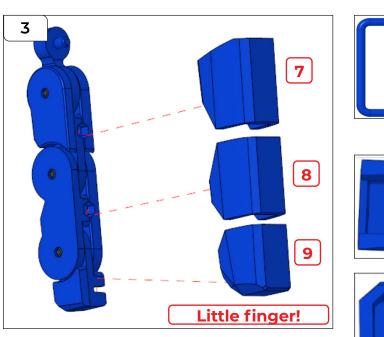
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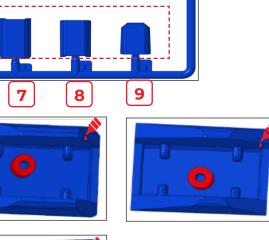
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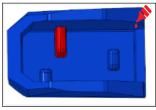
STEP 2

Snap No. 13 from **TR-3-40**. Snap No. 16 from **TR-3-41**. Fix 13 and 16 to 2F and secure them using **3x PB2x5 mm** screws.





TR-3-34



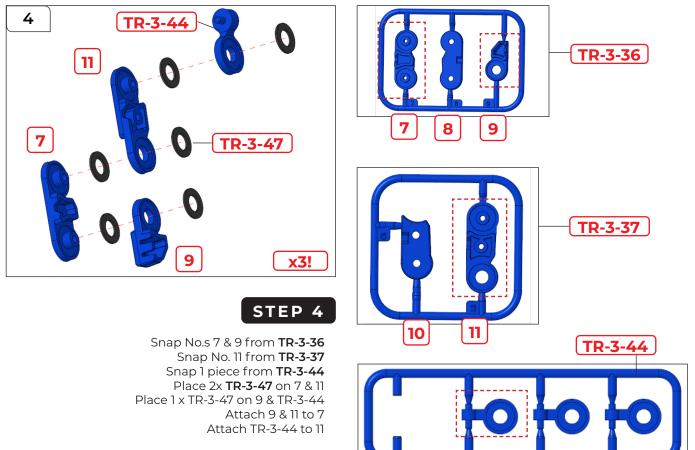


STEP 3

Apply glue as shown.

Snap No.s 7, 8 & 9 from TR-3-34.

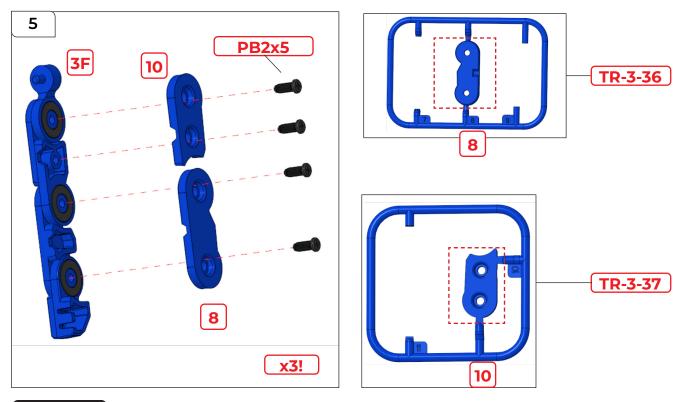
Fix 7, 8 & 9 to the assembly from step 2 as shown.



Repeat step 4 to make 3 sets

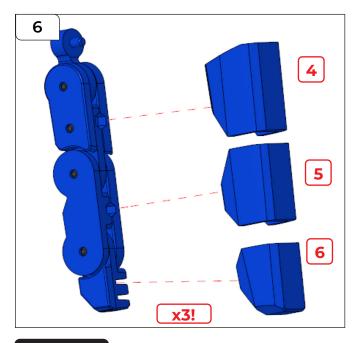


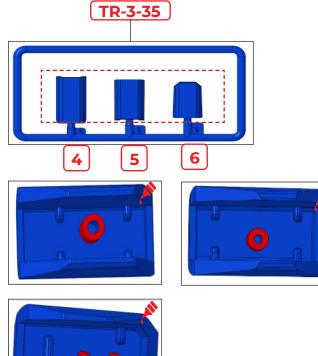
TR-3-47



STEP 5

Snap No. 8 from **TR-3-36** Snap No. 10 from **TR-3-37** Attach 8 & 10 to the assembly from step 4 and secure using **4x PB2x5 mm** screws. Repeat this step to make 3 sets.

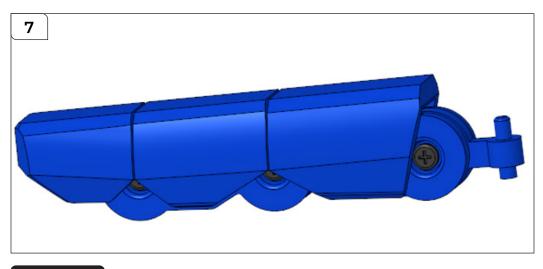




STEP 6

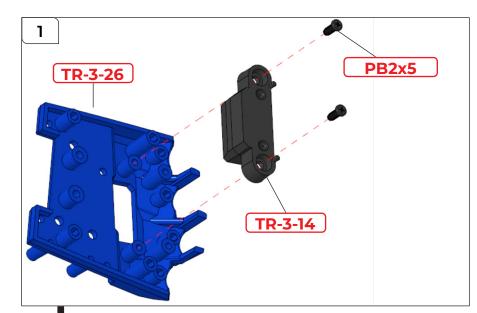
Snap No.s 4, 5 & 6 from **TR-3-35** Apply glue as shown Fix 4, 5 & 6 to the assembly from step 5 as shown. Repeat 3 times to complete 3 finger sets.

AGORAMODELS





Your 3 sets of fingers should now look like this.

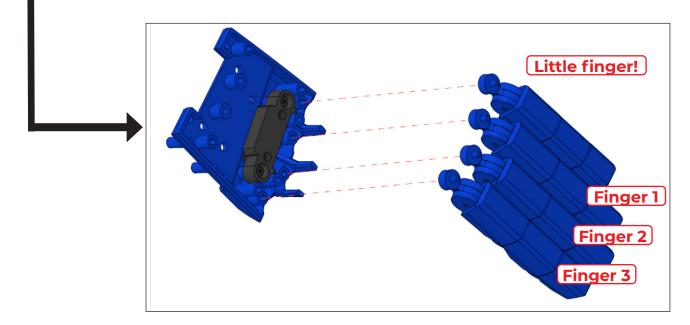


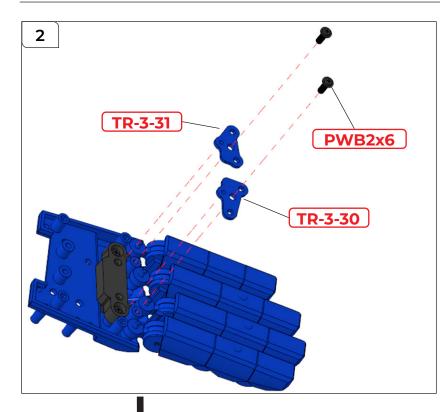
STEP 1

Attach TR-3-14 to TR-3-26 and secure together using 2x PB2x5 mm screws.

Attach the little finger and 3 sets of fingers as shown below.

Note, in this step and the step that follows, you may find it easier to attach two adjoining fingers at a time rather than all four fingers together.

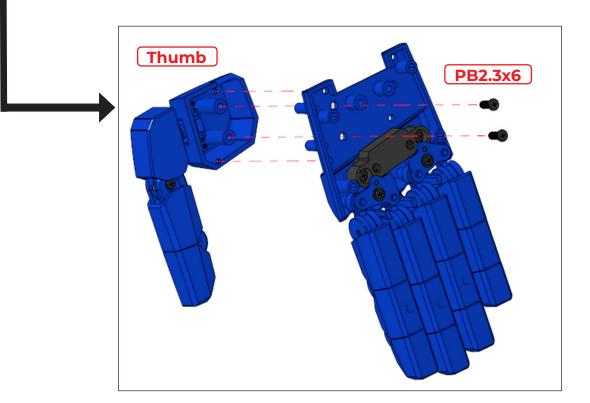


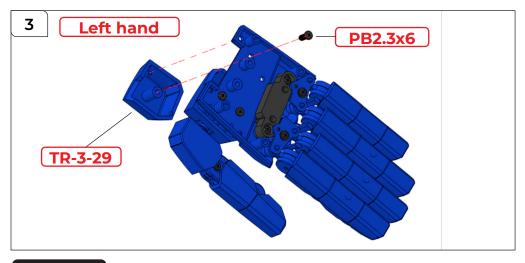


STEP 2

Attach **TR-3-31** and **TR-3-30** to the assembly from step 1 and secure them using **2x PWB2x6 mm** screws.

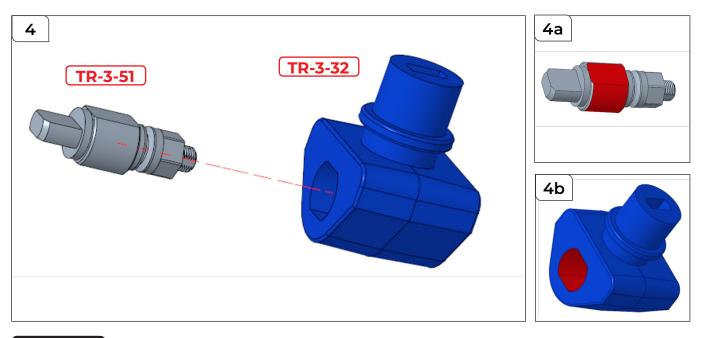
Then attach the thumb to the palm, securing them using **2x PB2.3x6 mm** screws.





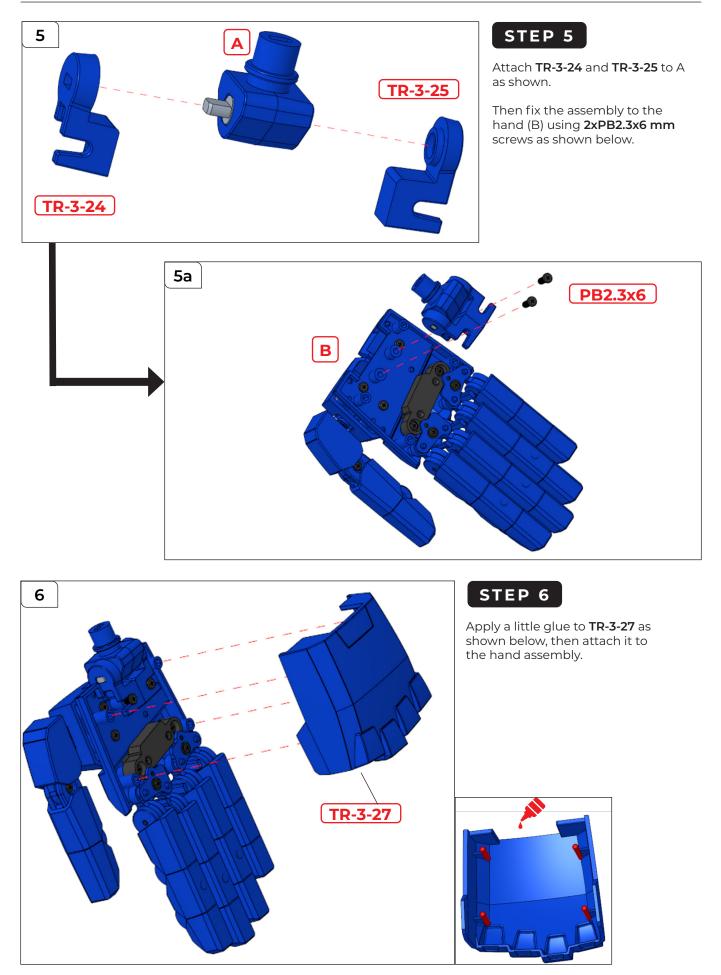
STEP 3

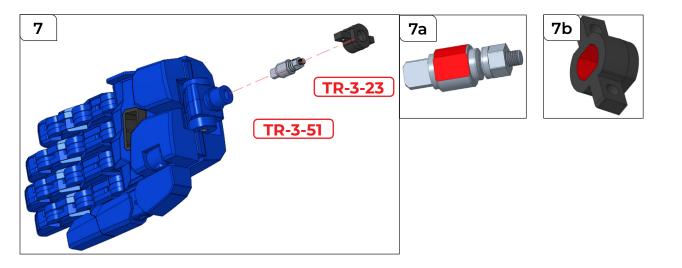
Attach **TR-3-29** to the left hand as shown. Use **1x PB2.3x6 mm** screw to secure it in place with the thumb.

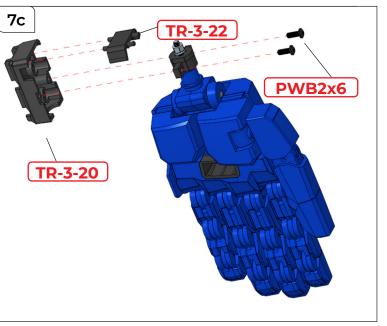


STEP 4

Insert **TR-3-51** into **TR-3-32**, checking the orientation of the parts as shown in red in 4a and 4b. You may need a small hammer for this.





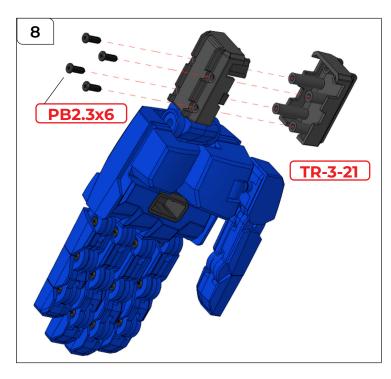


STEP 7

Attach **TR-3-51** and **TR-3-23** to the left hand as shown, checking the orientation as shown in 7a and 7b.

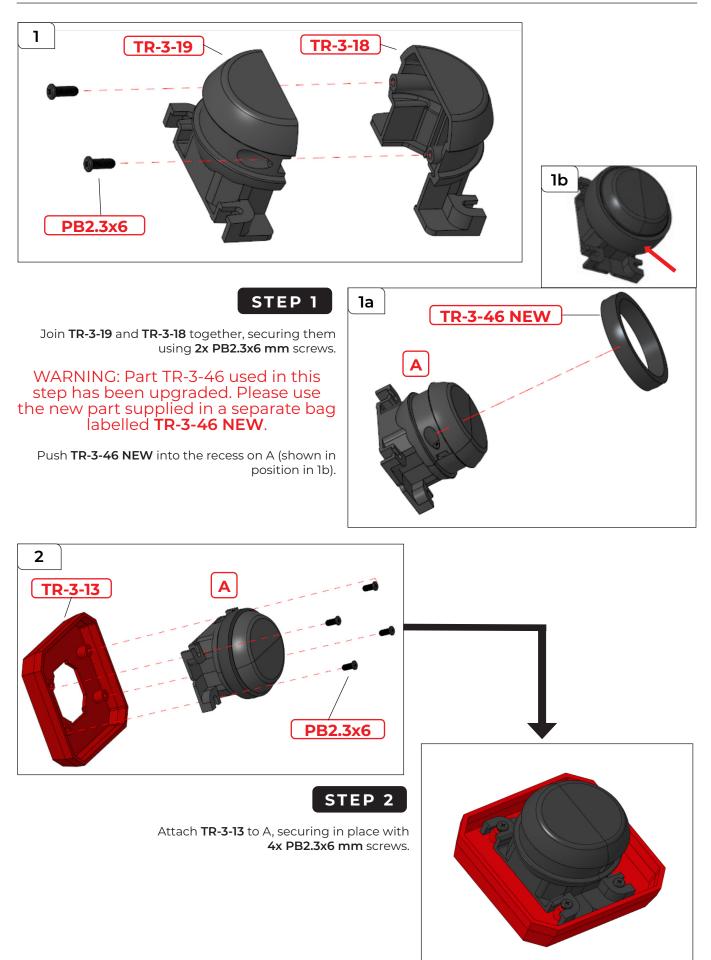
Then place **TR-3-22** on **TR-3-20** before attaching TR-3-20 to TR-3-23 on the hand as shown. Secure parts in place using **2x PWB2x6 mm** screws.

Note, part TR-3-22 will be secured in place in the next step.

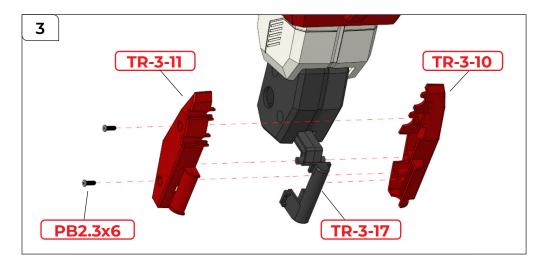


STEP 8

Attach **TR-3-21** to the hand, securing it in place as shown using **4x PB2.3x6 mm** screws.



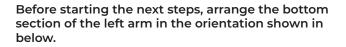
Assembling the Left Arm

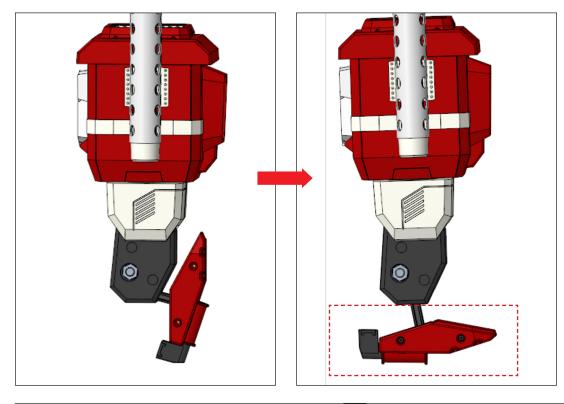


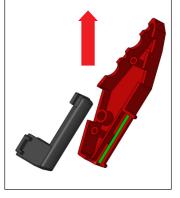
STEP 3

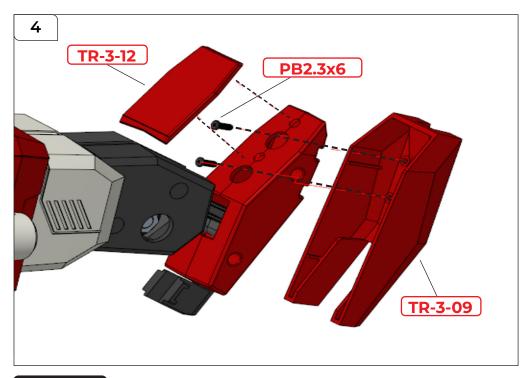
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Attach **TR-3-11, 10 & 17** to the left arm, completed in pack 2. The images to the right show the correct orientation for these parts. Secure together using **2x PB2.3x6 mm** screws.



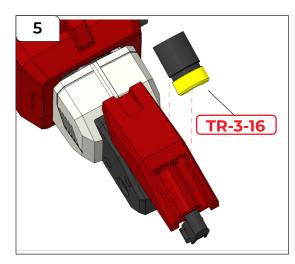






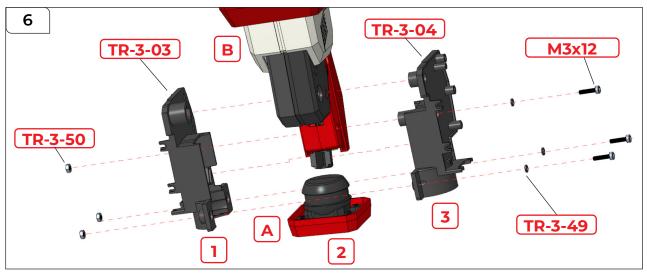
STEP 4

Attach **TR-3-09** onto the arm assembly and secure it using **2x PB2.3x6 mm** screws. Fix **TR-3-12** to the arm as shown in 4.



STEP 5

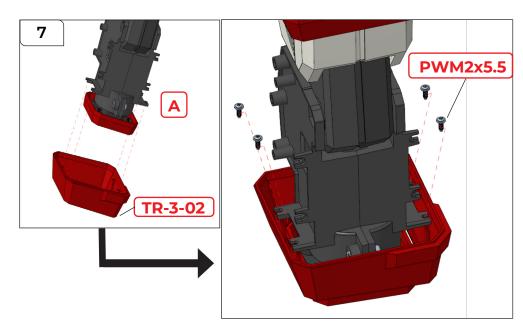
Attach TR-3-16 to the arm.



STEP 6

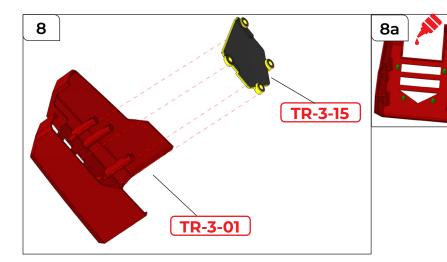
Attach assembly A, TR-3-03 and TR-3-04 to assembly B.

Thread **3x TR-3-49** onto **3x M3x12 mm** screws, then feed them through the screw holes as shown. Secure in place using **3x TR-3-50** nuts.



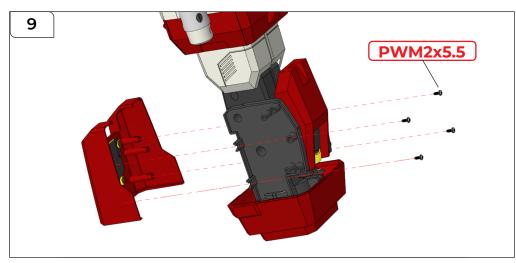


Attach **TR-3-02** to A as shown in 7. Secure it in place using **4x PWM2x5.5** screws.



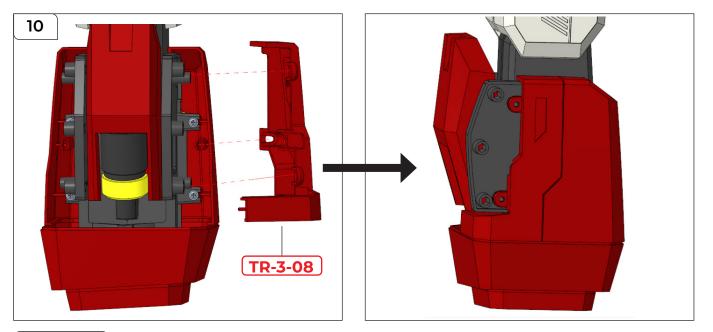
STEP 8

Apply a little glue to **TR-3-01** (indicated by the green area in 8a) before attaching it to **TR-3-15** as shown.



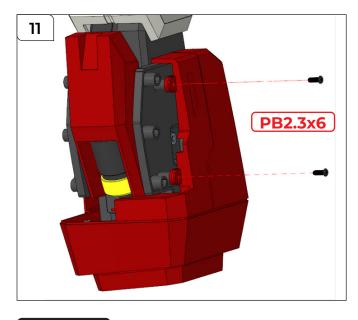
STEP 9

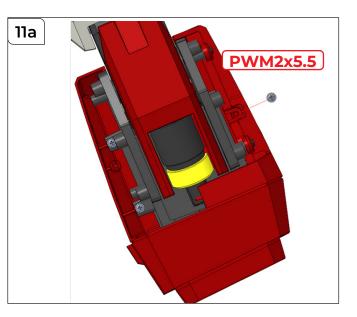
Attach the assembly from step 8 to the arm as shown. Secure it in place using **4x PWM2x5.5 mm** screws.



STEP 10

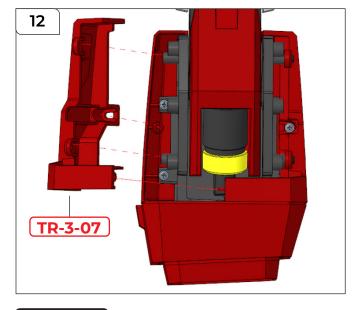
Attach TR-3-08 to the arm, as shown.

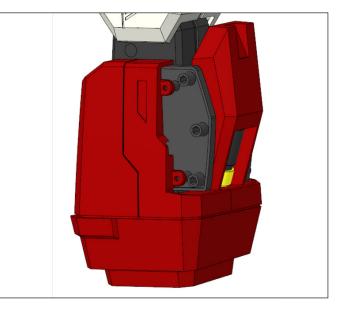




STEP 11

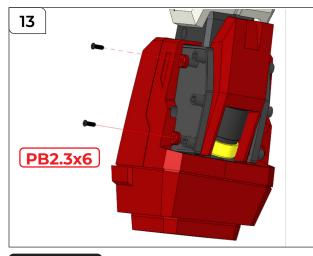
Secure TR-3-08 to the arm using 2x PB2.3x6 mm screws and 1x PWM2x5.5 mm screw as shown in 11 and 11a above.

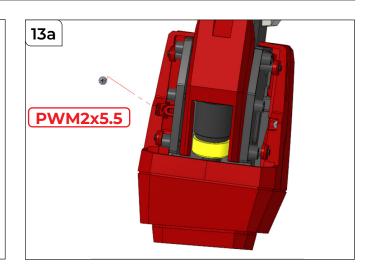




STEP 12

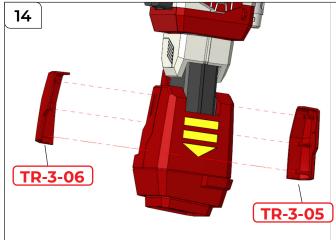
Attach TR-3-07 to the other side of the arm as shown.

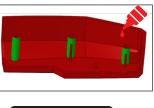


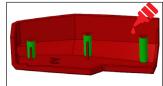


STEP 13

Secure TR-3-07 to the arm using 2x PB2.3x6 mm screws and 1x PWM2x5.5 mm screw as shown in 13 and 13a above.

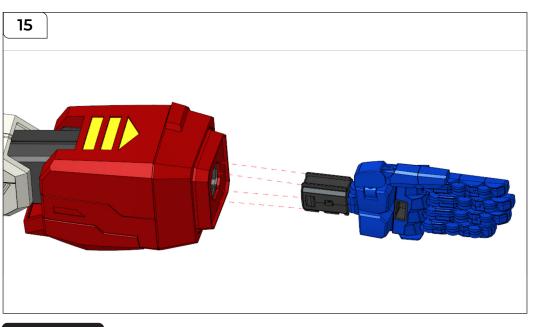






STEP 14

Test fit **TR-3-05 and 06** as shown, then apply a little glue (indicated by the green areas in the images above) before fixing them in place.



STEP 15

Push the hand assembly into the end of the arm assembly as shown.

